## Spring 2010

## Solution to Homework Assignment No. 1

**1.** (a) (i) Perform elimination as follows:

$$\begin{bmatrix} 2 & 1 & 0 & 0 & | & 0 \\ 1 & 2 & 1 & 0 & | & 0 \\ 0 & 1 & 2 & 1 & | & 0 \\ 0 & 0 & 1 & 2 & | & 5 \end{bmatrix} \implies \begin{bmatrix} 2 & 1 & 0 & 0 & | & 0 \\ 0 & \frac{3}{2} & 1 & 0 & | & 0 \\ 0 & 0 & 1 & 2 & | & 5 \end{bmatrix}$$
(subtract 1/2 × row 1)  
$$\implies \begin{bmatrix} 2 & 1 & 0 & 0 & | & 0 \\ 0 & \frac{3}{2} & 1 & 0 & | & 0 \\ 0 & 0 & \frac{4}{3} & 1 & | & 0 \\ 0 & 0 & 1 & 2 & | & 5 \end{bmatrix}$$
(subtract 2/3 × row 2)  
$$\implies \begin{bmatrix} 2 & 1 & 0 & 0 & | & 0 \\ 0 & 0 & \frac{4}{3} & 1 & | & 0 \\ 0 & 0 & \frac{4}{3} & 1 & | & 0 \\ 0 & 0 & \frac{4}{3} & 1 & | & 0 \\ 0 & 0 & 0 & \frac{5}{4} & | & 5 \end{bmatrix}$$
(subtract 3/4 × row 3)

This system is equivalent to

$$\begin{bmatrix} 2 & 1 & 0 & 0 \\ 0 & \frac{3}{2} & 1 & 0 \\ 0 & 0 & \frac{4}{3} & 1 \\ 0 & 0 & 0 & \frac{5}{4} \end{bmatrix} \begin{bmatrix} x \\ y \\ z \\ t \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 5 \end{bmatrix}.$$

Then we can solve the equations by back substitution as

$$\begin{cases} 2x + y = 0\\ \frac{3}{2}y + z = 0\\ \frac{4}{3}z + t = 0\\ \frac{5}{4}t = 5 \end{cases} \Rightarrow \begin{cases} x = -\frac{1}{2}y\\ y = -\frac{2}{3}z\\ z = -\frac{3}{4}t\\ t = 4 \end{cases} \Rightarrow \begin{cases} x = -1\\ y = 2\\ z = -3\\ t = 4. \end{cases}$$

The pivots are 2, 3/2, 4/3, and 5/4, and the solution is (x, y, z, t) = (-1, 2, -3, 4).

(ii) Perform elimination as follows:

$$\begin{bmatrix} 2 & -1 & 0 & 0 & | & 0 \\ -1 & 2 & -1 & 0 & | & 0 \\ 0 & -1 & 2 & -1 & | & 0 \\ 0 & 0 & -1 & 2 & | & 5 \end{bmatrix} \implies \begin{bmatrix} 2 & -1 & 0 & 0 & | & 0 \\ 0 & -1 & 2 & -1 & | & 0 \\ 0 & 0 & -1 & 2 & | & 5 \end{bmatrix}$$
(subtract  $-1/2 \times \text{row 1}$ )  
$$\implies \begin{bmatrix} 2 & -1 & 0 & 0 & | & 0 \\ 0 & \frac{3}{2} & -1 & 0 & | & 0 \\ 0 & 0 & \frac{4}{3} & -1 & | & 0 \\ 0 & 0 & -1 & 2 & | & 5 \end{bmatrix}$$
(subtract  $-2/3 \times \text{row 2}$ )  
$$\implies \begin{bmatrix} 2 & -1 & 0 & 0 & | & 0 \\ 0 & 0 & \frac{4}{3} & -1 & | & 0 \\ 0 & 0 & \frac{4}{3} & -1 & | & 0 \\ 0 & 0 & \frac{4}{3} & -1 & | & 0 \\ 0 & 0 & \frac{4}{3} & -1 & | & 0 \\ 0 & 0 & 0 & \frac{4}{3} & -1 & | & 0 \\ 0 & 0 & 0 & \frac{4}{3} & -1 & | & 0 \\ 0 & 0 & 0 & \frac{5}{4} & | & 5 \end{bmatrix}$$
(subtract  $-3/4 \times \text{row 3}$ )

This system is equivalent to

$$\begin{bmatrix} 2 & -1 & 0 & 0 \\ 0 & \frac{3}{2} & -1 & 0 \\ 0 & 0 & \frac{4}{3} & -1 \\ 0 & 0 & 0 & \frac{5}{4} \end{bmatrix} \begin{bmatrix} x \\ y \\ z \\ t \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 5 \end{bmatrix}$$

Then we can solve the equations by back substitution as

$$\begin{cases} 2x - y = 0\\ \frac{3}{2}y - z = 0\\ \frac{4}{3}z - t = 0\\ \frac{5}{4}t = 5 \end{cases} \Rightarrow \begin{cases} x = \frac{1}{2}y\\ y = \frac{2}{3}z\\ z = \frac{3}{4}t\\ t = 4 \end{cases} \Rightarrow \begin{cases} x = 1\\ y = 2\\ z = 3\\ t = 4. \end{cases}$$

The pivots are 2, 3/2, 4/3, and 5/4, and the solution is (x, y, z, t) = (1, 2, 3, 4).

(b) Do elimination once more, and we can obtain the fifth pivot equal to 2 − (5/4)<sup>-1</sup> = 6/5. Observe the pivots, 2, 3/2, 4/3, 5/4, 6/5, ..., and we can guess that the *n*th pivot is equal to (n + 1)/n.
Claim: The *n*th pivot is (n + 1)/n.
Proof: When n = 1, the 1st pivot is 2/1.
Assume when n = k − 1, the kth pivot is k/(k − 1).
By observing the procedure of elimination, we can know that the kth pivot is generated in the following way:

the *k*th pivot = 
$$2 - \frac{1}{\text{the } (k-1)\text{th pivot}} = 2 - \frac{k-1}{k} = \frac{k+1}{k}$$
.

By induction, we conclude that the *n*th pivot is (n+1)/n.

2. Pascal's triangle is defined as



The *i*th row of Pascal's triangle has *i* components denoted as  $[P_{i,1}, P_{i,2}, ..., P_{i,i}]$  which are derived by

$$[P_{i,1}, P_{i,2}, \dots, P_{i,i}] = [P_{i-1,1}, P_{i-1,2}, \dots, P_{i-1,i-1}, 0] + [0, P_{i-1,1}, P_{i-1,2}, \dots, P_{i-1,i-1}].$$

For example, the components of the 4th row are given by

$$[1, 3, 3, 1] = [1, 2, 1, 0] + [0, 1, 2, 1]$$

To reduce the Pasical matrix to a smaller one as

$$\begin{bmatrix} 1 & 0 & 0 & 0 \\ 1 & 1 & 0 & 0 \\ 1 & 2 & 1 & 0 \\ 1 & 3 & 3 & 1 \end{bmatrix} \Longrightarrow \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 1 & 1 & 0 \\ 0 & 1 & 2 & 1 \end{bmatrix}$$

we can subtract the (i - 1)th row from the *i*th row of the original matrix for i = 2, 3, 4. This process can be expressed by

$$\begin{bmatrix} 1 & 0 & 0 & 0 \\ -1 & 1 & 0 & 0 \\ 0 & -1 & 1 & 0 \\ 0 & 0 & -1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 \\ 1 & 1 & 0 & 0 \\ 1 & 2 & 1 & 0 \\ 1 & 3 & 3 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 1 & 1 & 0 \\ 0 & 1 & 2 & 1 \end{bmatrix}.$$

Therefore, we have

$$\boldsymbol{E} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ -1 & 1 & 0 & 0 \\ 0 & -1 & 1 & 0 \\ 0 & 0 & -1 & 1 \end{bmatrix}.$$

In a similar way, we can reduce the Pascal matrix all the way to an identity matrix as

$\begin{bmatrix} 1 & 0 \end{bmatrix}$	0 (	0 ]	[1 (	0 (	0	] [	1	0	0	0	] [	1	0	0	0	1
1 1	0 (	0	0 1	0	0	1	0	1	0	0	$\Rightarrow$	0	1	0	0	)
1 2	1 (	$_{0} \mid \Longrightarrow$	0 1	. 1	0		0	0	1	0		0	0	1	0	·
1 3	3	1	0 1	2	1		0	0	1	1		0	0	0	1	

Therefore, we can have

$$\begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & -1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & -1 & 1 & 0 \\ 0 & 0 & -1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 \\ -1 & 1 & 0 & 0 \\ 0 & -1 & 1 & 0 \\ 0 & 0 & -1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 \\ 1 & 1 & 0 & 0 \\ 1 & 2 & 1 & 0 \\ 1 & 3 & 3 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}.$$

The desired matrix is then given by

$$M = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & -1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & -1 & 1 & 0 \\ 0 & 0 & -1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 \\ -1 & 1 & 0 & 0 \\ 0 & -1 & 1 & 0 \\ 0 & 0 & -1 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ -1 & 1 & 0 & 0 \\ 1 & -2 & 1 & 0 \\ -1 & 3 & -3 & 1 \end{bmatrix}.$$

**3.** (a) Using the Gauss-Jordan method, we can have

$$\begin{bmatrix} \mathbf{A} \mid \mathbf{I} \end{bmatrix} = \begin{bmatrix} 2 & 1 & 1 & | & 1 & 0 & 0 \\ 1 & 2 & 1 & | & 0 & 1 & 0 \\ 1 & 1 & 2 & | & 0 & 0 & 1 \end{bmatrix}$$

$$\implies \begin{bmatrix} 2 & 1 & 1 & | & 1 & 0 & 0 \\ 0 & \frac{3}{2} & \frac{1}{2} & | & -\frac{1}{2} & 1 & 0 \\ 0 & \frac{1}{2} & \frac{3}{2} & | & -\frac{1}{2} & 0 & 1 \end{bmatrix}$$

$$\implies \begin{bmatrix} 2 & 1 & 1 & | & 1 & 0 & 0 \\ 0 & \frac{3}{2} & \frac{1}{2} & | & -\frac{1}{2} & 1 & 0 \\ 0 & 0 & \frac{4}{3} & | & -\frac{1}{3} & -\frac{1}{3} & 1 \end{bmatrix}$$

$$\implies \begin{bmatrix} 2 & 1 & 0 & | & \frac{5}{4} & \frac{1}{4} & -\frac{3}{4} \\ 0 & \frac{3}{2} & 0 & | & -\frac{3}{8} & \frac{9}{8} & -\frac{3}{8} \\ 0 & 0 & \frac{4}{3} & | & -\frac{1}{3} & -\frac{1}{3} & 1 \end{bmatrix}$$

$$\implies \begin{bmatrix} 2 & 0 & 0 & | & \frac{3}{2} & -\frac{1}{2} & -\frac{1}{2} \\ 0 & \frac{3}{2} & 0 & | & -\frac{3}{8} & \frac{9}{8} & -\frac{3}{8} \\ 0 & 0 & \frac{4}{3} & | & -\frac{1}{3} & -\frac{1}{3} & 1 \end{bmatrix}$$

$$\implies \begin{bmatrix} 1 & 0 & 0 & | & \frac{3}{4} & -\frac{1}{4} & -\frac{1}{4} \\ 0 & 1 & 0 & | & -\frac{1}{4} & \frac{3}{4} & -\frac{1}{4} \\ 0 & 0 & 1 & | & -\frac{1}{4} & -\frac{1}{4} & -\frac{4}{4} \end{bmatrix} = \begin{bmatrix} \mathbf{I} \mid \mathbf{A}^{-1} \end{bmatrix}.$$

The inverse is hence

$$\boldsymbol{A^{-1}} = \begin{bmatrix} \frac{3}{4} & -\frac{1}{4} & -\frac{1}{4} \\ -\frac{1}{4} & \frac{3}{4} & -\frac{1}{4} \\ -\frac{1}{4} & -\frac{1}{4} & -\frac{3}{4} \end{bmatrix} = \frac{1}{4} \begin{bmatrix} 3 & -1 & -1 \\ -1 & 3 & -1 \\ -1 & -1 & -3 \end{bmatrix}.$$

(b) Using the Gauss-Jordan method, we can have

$$\begin{bmatrix} B & | I \end{bmatrix} = \begin{bmatrix} 2 & -1 & -1 & | 1 & 0 & 0 \\ -1 & 2 & -1 & | & 0 & 1 & 0 \\ -1 & -1 & 2 & | & 0 & 0 & 1 \end{bmatrix}$$
$$\implies \begin{bmatrix} 2 & -1 & -1 & | & 1 & 0 & 0 \\ 0 & \frac{3}{2} & -\frac{3}{2} & | & \frac{1}{2} & 1 & 0 \\ 0 & -\frac{3}{2} & \frac{3}{2} & | & \frac{1}{2} & 0 & 1 \end{bmatrix}$$
$$\implies \begin{bmatrix} 2 & -1 & -1 & | & 1 & 0 & 0 \\ 0 & \frac{3}{2} & -\frac{3}{2} & | & \frac{1}{2} & 1 & 0 \\ 0 & 0 & 0 & | & 1 & 1 & 1 \end{bmatrix}.$$

Since we cannot obtain three nonzero pivots,  $\boldsymbol{B}^{-1}$  does not exist.

4. (a) Using the Gauss-Jordan method, we can have

$$\begin{bmatrix} \mathbf{A} \mid \mathbf{I} \end{bmatrix} = \begin{bmatrix} 1 & -1 & 1 & -1 & | & 1 & 0 & 0 & 0 \\ 0 & 1 & -1 & 1 & | & 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & -1 & | & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 & | & 0 & 0 & 0 & 1 \end{bmatrix}$$

$$\implies \begin{bmatrix} 1 & -1 & 1 & 0 & | & 1 & 0 & 0 & 1 \\ 0 & 1 & -1 & 0 & | & 0 & 1 & 0 & -1 \\ 0 & 0 & 1 & 0 & | & 0 & 0 & 0 & 1 \end{bmatrix}$$

$$\implies \begin{bmatrix} 1 & -1 & 0 & 0 & | & 1 & 0 & -1 & 0 \\ 0 & 1 & 0 & 0 & | & 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 & | & 0 & 0 & 0 & 1 \end{bmatrix}$$

$$\implies \begin{bmatrix} 1 & 0 & 0 & 0 & | & 1 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 & | & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 1 & | & 0 & 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} \mathbf{I} \mid \mathbf{A}^{-1} \end{bmatrix}.$$

We can then obtain

$$\boldsymbol{A^{-1}} = \left[ \begin{array}{rrrr} 1 & 1 & 0 & 0 \\ 0 & 1 & 1 & 0 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 1 \end{array} \right].$$

(b) Extend  $\boldsymbol{A}$  to a  $5\times 5$  "alternating matrix" as

$$\boldsymbol{A}_{5\times5} = \begin{bmatrix} 1 & -1 & 1 & -1 & 1 \\ 0 & 1 & -1 & 1 & -1 \\ 0 & 0 & 1 & -1 & 1 \\ 0 & 0 & 0 & 1 & -1 \\ 0 & 0 & 0 & 0 & 1 \end{bmatrix}.$$

From the result of (a), we guess

$$\boldsymbol{A}_{5\times5}^{-1} = \begin{bmatrix} 1 & 1 & 0 & 0 & 0 \\ 0 & 1 & 1 & 0 & 0 \\ 0 & 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 0 & 1 \end{bmatrix}.$$

Since

$$\begin{bmatrix} 1 & -1 & 1 & -1 & 1 \\ 0 & 1 & -1 & 1 & -1 \\ 0 & 0 & 1 & -1 & 1 \\ 0 & 0 & 0 & 1 & -1 \\ 0 & 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 1 & 0 & 0 & 0 \\ 0 & 1 & 1 & 0 & 0 \\ 0 & 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 1 \end{bmatrix} = \boldsymbol{I}$$

and

$$\begin{bmatrix} 1 & 1 & 0 & 0 & 0 \\ 0 & 1 & 1 & 0 & 0 \\ 0 & 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & -1 & 1 & -1 & 1 \\ 0 & 1 & -1 & 1 & -1 \\ 0 & 0 & 1 & -1 & 1 \\ 0 & 0 & 0 & 1 & -1 \\ 0 & 0 & 0 & 1 & -1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 1 \end{bmatrix} = \mathbf{I}$$

we have confirmed that the inverse of the matrix is indeed

$$\boldsymbol{A}_{5\times5}^{-1} = \begin{bmatrix} 1 & 1 & 0 & 0 & 0 \\ 0 & 1 & 1 & 0 & 0 \\ 0 & 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 0 & 1 \end{bmatrix}.$$

5. (a) Performing elimination, we can have

$$\boldsymbol{A} = \begin{bmatrix} 1 & 1 & 0 \\ 1 & 2 & 1 \\ 0 & 1 & 2 \end{bmatrix} \stackrel{\boldsymbol{E}_{21}}{\Longrightarrow} \begin{bmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \\ 0 & 1 & 2 \end{bmatrix} \stackrel{\boldsymbol{E}_{32}}{\Longrightarrow} \begin{bmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{bmatrix} = \boldsymbol{U}.$$

This procedure can be viewed as

$$\boldsymbol{E}_{32}\boldsymbol{E}_{21}\boldsymbol{A} = \boldsymbol{U}$$

where

$$\boldsymbol{E}_{21} = \begin{bmatrix} 1 & 0 & 0 \\ -1 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \text{ and } \boldsymbol{E}_{32} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & -1 & 1 \end{bmatrix}.$$

Then we have

$$A = E_{21}^{-1} E_{32}^{-1} U = L U$$

where

$$\boldsymbol{L} = \boldsymbol{E}_{21}^{-1} \boldsymbol{E}_{32}^{-1} = \begin{bmatrix} 1 & 0 & 0 \\ 1 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 1 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 1 & 1 & 0 \\ 0 & 1 & 1 \end{bmatrix}$$

We find that  $\boldsymbol{U} = \boldsymbol{L}^T = \boldsymbol{D}\boldsymbol{L}^T$  where  $\boldsymbol{D} = \boldsymbol{I}$ . We can therefore factor  $\boldsymbol{A} = \boldsymbol{L}\boldsymbol{U}$  and  $\boldsymbol{A} = \boldsymbol{L}\boldsymbol{D}\boldsymbol{L}^T$  as

$$\begin{bmatrix} 1 & 1 & 0 \\ 1 & 2 & 1 \\ 0 & 1 & 2 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 1 & 1 & 0 \\ 0 & 1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{bmatrix}$$
$$\begin{bmatrix} 1 & 1 & 0 \\ 1 & 2 & 1 \\ 0 & 1 & 2 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 1 & 1 & 0 \\ 0 & 1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 1 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

and

(b) Performing elimination, we can have

$$\boldsymbol{A} = \begin{bmatrix} a & a & 0 \\ a & a+b & b \\ 0 & b & b+c \end{bmatrix} \stackrel{\boldsymbol{E}_{21}}{\Longrightarrow} \begin{bmatrix} a & a & 0 \\ 0 & b & b \\ 0 & b & b+c \end{bmatrix} \stackrel{\boldsymbol{E}_{32}}{\Longrightarrow} \begin{bmatrix} a & a & 0 \\ 0 & b & b \\ 0 & 0 & c \end{bmatrix} = \boldsymbol{U}.$$

Since  $E_{21}$  and  $E_{32}$  are the same as those in (a), we know that A has the same L, too. The factorization A = LU is hence

$$\begin{bmatrix} a & a & 0 \\ a & a+b & b \\ 0 & b & b+c \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 1 & 1 & 0 \\ 0 & 1 & 1 \end{bmatrix} \begin{bmatrix} a & a & 0 \\ 0 & b & b \\ 0 & 0 & c \end{bmatrix}.$$

We can further factor  $\boldsymbol{U}$  as

$$\boldsymbol{U} = \begin{bmatrix} a & a & 0 \\ 0 & b & b \\ 0 & 0 & c \end{bmatrix} = \begin{bmatrix} a & 0 & 0 \\ 0 & b & 0 \\ 0 & 0 & c \end{bmatrix} \begin{bmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{bmatrix} = \boldsymbol{D} \boldsymbol{L}^{T}.$$

The factorization  $\boldsymbol{A} = \boldsymbol{L} \boldsymbol{D} \boldsymbol{L}^T$  is thus given by

$$\begin{bmatrix} a & a & 0 \\ a & a+b & b \\ 0 & b & b+c \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 1 & 1 & 0 \\ 0 & 1 & 1 \end{bmatrix} \begin{bmatrix} a & 0 & 0 \\ 0 & b & 0 \\ 0 & 0 & c \end{bmatrix} \begin{bmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{bmatrix}.$$

6. (a) Given  $\boldsymbol{A} = \boldsymbol{L}_1 \boldsymbol{D}_1 \boldsymbol{U}_1$  and  $\boldsymbol{A} = \boldsymbol{L}_2 \boldsymbol{D}_2 \boldsymbol{U}_2$ , we can have

$$egin{aligned} & m{L}_2 m{D}_2 m{U}_2 = m{L}_1 m{D}_1 m{U}_1 \ & \implies & m{L}_1^{-1} (m{L}_2 m{D}_2 m{U}_2) m{U}_2^{-1} = m{L}_1^{-1} (m{L}_1 m{D}_1 m{U}_1) m{U}_2^{-1} \ & \implies & m{L}_1^{-1} m{L}_2 m{D}_2 = m{D}_1 m{U}_1 m{U}_2^{-1}. \end{aligned}$$

In order to explain why one side is lower triangular and the other side is upper triangular, we need to prove two claims first.

**Claim 1:** The inverse of a lower (upper) triangular matrix with unit diagonal is also lower (upper) triangular with unit diagonal.

**Proof:** (Lower triangular case)

Suppose L is an  $n \times n$  lower triangular matrix with unit diagonal and  $L^{-1}$  exists. We can use Gauss-Jordan method to find  $L^{-1}$ . We only need to do the Gaussian part. It means that the required operations are only to subtract the *i*th row from the *j*th row for i < j. Therefore, we can have

$$\begin{bmatrix} \mathbf{L} & | & \mathbf{I} \end{bmatrix} = \begin{bmatrix} 1 & 0 & \cdots & 0 & | & 1 & 0 & 0 & 0 \\ l_{2,1} & 1 & \ddots & \vdots & | & 0 & 1 & 0 & 0 \\ \vdots & \ddots & \ddots & 0 & | & 0 & 0 & 1 & 0 \\ l_{n,1} & \cdots & l_{n,n-1} & 1 & | & 0 & 0 & 0 & 1 \end{bmatrix}$$
$$\implies \begin{bmatrix} 1 & 0 & 0 & 0 & | & 1 & 0 & \cdots & 0 \\ 0 & 1 & 0 & 0 & | & l'_{2,1} & 1 & \ddots & \vdots \\ 0 & 0 & 1 & 0 & | & \vdots & \ddots & \ddots & 0 \\ 0 & 0 & 0 & 1 & | & l'_{n,1} & \cdots & l'_{n,n-1} & 1 \end{bmatrix} = \begin{bmatrix} \mathbf{I} & | & \mathbf{L}^{-1} \end{bmatrix}.$$

It is clear that  $L^{-1}$  is lower triangular with unit diagonal. The upper triangular case can be proved similarly.

**Claim 2:** The product of two lower (upper) triangular matrices with unit diagonal is also lower (upper) triangular with unit diagonal.

**Proof:** (Lower triangular case)

Suppose A and B are two  $n \times n$  lower triangular matrices with unit diagonal. We have  $A_{i,j} = 0$  if i < j and  $A_{i,j} = 1$  if i = j, and  $B_{i,j} = 0$  if i < j and  $B_{i,j} = 1$  if i = j. For  $1 \le i < j \le n$ , we have

$$(AB)_{i,j} = \sum_{k=1}^{n} A_{i,k} B_{k,j}$$
  
=  $\sum_{k=1}^{j-1} A_{i,k} B_{k,j} + \sum_{k=j}^{n} A_{i,k} B_{k,j}$   
=  $0 + 0$  ( $B_{i,k} = 0$  when  $k < j$ , and  $A_{i,k} = 0$  when  $i < j \le k$ .)  
=  $0$ .

Therefore, AB is lower triangular. For  $1 \le i = j \le n$ , we have

$$(AB)_{i,i} = \sum_{k=1}^{n} A_{i,k} B_{k,i}$$
  
=  $\sum_{k=1}^{i-1} A_{i,k} B_{k,i} + A_{i,i} B_{i,i} + \sum_{k=i+1}^{n} A_{i,k} B_{k,i}$   
=  $0 + 1 \cdot 1 + 0$  ( $B_{i,k} = 0$  when  $k < i$ ,  $A_{i,i} = B_{i,i} = 1$ , and  $A_{i,k} = 0$  when  $i < k$ )  
=  $1$ .

Therefore, AB has unit diagonal. We can conclude that AB is also lower triangular with unit diagonal. The upper triangular case can be proved similarly.

Let 
$$\boldsymbol{A} = \begin{bmatrix} \underline{\mathbf{a}}_1 \\ \underline{\mathbf{a}}_2 \\ \vdots \\ \underline{\mathbf{a}}_n \end{bmatrix}$$
, where  $\underline{\mathbf{a}}_i = [a_{i,1} \ a_{i,2} \ \cdots \ a_{i,n}]$ , and  $\boldsymbol{D}$  be a diagonal matrix

with diagonal elements  $d_1, d_2, ..., d_n$ . We can have

$$\boldsymbol{A}\boldsymbol{D} = \begin{bmatrix} \underline{\mathbf{a}}_1 \\ \underline{\mathbf{a}}_2 \\ \vdots \\ \underline{\mathbf{a}}_n \end{bmatrix} \begin{bmatrix} d_1 & 0 & \cdots & 0 \\ 0 & d_2 & 0 & \vdots \\ \vdots & \ddots & \ddots & \vdots \\ 0 & \cdots & 0 & d_n \end{bmatrix} = \begin{bmatrix} d_1\underline{\mathbf{a}}_1 \\ d_2\underline{\mathbf{a}}_2 \\ \vdots \\ d_n\underline{\mathbf{a}}_n \end{bmatrix}$$

and

$$\boldsymbol{D}\boldsymbol{A} = \begin{bmatrix} d_1 & 0 & \cdots & 0 \\ 0 & d_2 & 0 & \vdots \\ \vdots & \ddots & \ddots & \vdots \\ 0 & \cdots & 0 & d_n \end{bmatrix} \begin{bmatrix} \underline{\mathbf{a}}_1 \\ \underline{\mathbf{a}}_2 \\ \vdots \\ \underline{\mathbf{a}}_n \end{bmatrix} = \begin{bmatrix} d_1 \underline{\mathbf{a}}_1 \\ d_2 \underline{\mathbf{a}}_2 \\ \vdots \\ d_n \underline{\mathbf{a}}_n \end{bmatrix}$$

Therefore, a lower (upper) triangular matrix multiplied by a diagonal matrix is still a lower (upper) triangular matrix. Come back to  $\boldsymbol{L}_1^{-1}\boldsymbol{L}_2\boldsymbol{D}_2 = \boldsymbol{D}_1\boldsymbol{U}_1\boldsymbol{U}_2^{-1}$ . By Claim 1,  $\boldsymbol{L}_1^{-1}$  is lower triangular with unit diagonal. By Claim 2,  $\boldsymbol{L}_1^{-1}\boldsymbol{L}_2$  is lower triangular with unit diagonal. Therefore,  $\boldsymbol{L}_1^{-1}\boldsymbol{L}_2\boldsymbol{D}_2$  is lower triangular. Similarly,  $\boldsymbol{D}_1\boldsymbol{U}_1\boldsymbol{U}_2^{-1}$  is upper triangular.

- (b) Let  $M = L_1^{-1}L_2D_2 = D_1U_1U_2^{-1}$ . Then M is both lower and upper triangular, which implies that M is a diagonal matrix.
  - (i) Since  $U_1U_2^{-1}$  is with unit diagonal,  $M = D_1U_1U_2^{-1}$  has the same diagonal as  $D_1$ . It implies that  $M = D_1$ . Similarly, we can have  $M = D_2$ . Therefore,  $D_1 = D_2$ .
  - (ii) For  $\boldsymbol{M} = \boldsymbol{L}_1^{-1} \boldsymbol{L}_2 \boldsymbol{D}_2 = \boldsymbol{D}_2$ , we have  $\boldsymbol{L}_1^{-1} \boldsymbol{L}_2 = \boldsymbol{I}$ . Since the inverse matrix is unique, we have  $\boldsymbol{L}_2 = (\boldsymbol{L}_1^{-1})^{-1} = \boldsymbol{L}_1$ .
  - (iii) Similarly, for  $\boldsymbol{M} = \boldsymbol{D}_1 \boldsymbol{U}_1 \boldsymbol{U}_2^{-1} = \boldsymbol{D}_1$ , we have  $\boldsymbol{U}_1 \boldsymbol{U}_2^{-1} = \boldsymbol{I}$ . It then implies that  $\boldsymbol{U}_1 = (\boldsymbol{U}_2^{-1})^{-1} = \boldsymbol{U}_2$ .
- 7. Since A and B are symmetric matrices, it implies that  $A^T = A$  and  $B^T = B$ .
  - (a) We have

$$(\mathbf{A}^2)^T = (\mathbf{A}\mathbf{A})^T = (\mathbf{A}^T\mathbf{A}^T) = \mathbf{A}\mathbf{A} = \mathbf{A}^2.$$

Therefore,  $A^2$  is symmetric, and so is  $B^2$ . Since

$$(A^{2} - B^{2})^{T} = (A^{2})^{T} - (B^{2})^{T} = A^{2} - B^{2}$$

 $A^2 - B^2$  is also symmetric.

(b) The product  $(\mathbf{A} + \mathbf{B})(\mathbf{A} - \mathbf{B})$  is not always symmetric. A counterexample is given as follows. Consider two symmetric matrices

	Γ1	1	2		[1	0	1]
$oldsymbol{A}=$	1	1	0	and $\boldsymbol{B} =$	0	1	0
	2	0	1		1	0	1

and we can have

$$(\mathbf{A} + \mathbf{B})(\mathbf{A} - \mathbf{B}) = \begin{bmatrix} 2 & 1 & 3 \\ 1 & 2 & 0 \\ 3 & 0 & 2 \end{bmatrix} \begin{bmatrix} 0 & 1 & 1 \\ 1 & 0 & 0 \\ 1 & 0 & 0 \end{bmatrix} = \begin{bmatrix} 4 & 2 & 2 \\ 2 & 1 & 1 \\ 2 & 3 & 3 \end{bmatrix}$$

which is not a symmetric matrix.

- (c) Since  $(\boldsymbol{A}\boldsymbol{B}\boldsymbol{A})^T = \boldsymbol{A}^T\boldsymbol{B}^T\boldsymbol{A}^T = \boldsymbol{A}\boldsymbol{B}\boldsymbol{A}$ ,  $\boldsymbol{A}\boldsymbol{B}\boldsymbol{A}$  is symmetric.
- (d) The product **ABAB** is not always symmetric. A counterexample is given as follows. Consider two symmetric matrices

$$\boldsymbol{A} = \begin{bmatrix} 1 & 1 & 2 \\ 1 & 1 & 0 \\ 2 & 0 & 1 \end{bmatrix} \text{ and } \boldsymbol{B} = \begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & 0 \\ 1 & 0 & 1 \end{bmatrix}$$

and we can have

$$\boldsymbol{ABAB} = \begin{bmatrix} 19 & 4 & 19 \\ 7 & 2 & 7 \\ 18 & 3 & 18 \end{bmatrix}$$

which is not a symmetric matrix.

8. (a) First do row exchange as

$$\boldsymbol{A} = \begin{bmatrix} 1 & 2 & 0 \\ 2 & 4 & 1 \\ 1 & 1 & 3 \end{bmatrix} \xrightarrow{\boldsymbol{P}_{13}} \begin{bmatrix} 1 & 1 & 3 \\ 2 & 4 & 1 \\ 1 & 2 & 0 \end{bmatrix} = \boldsymbol{P}\boldsymbol{A}$$

and then perform elimination as

$$\begin{bmatrix} 1 & 1 & 3 \\ 2 & 4 & 1 \\ 1 & 2 & 0 \end{bmatrix} \xrightarrow{\mathbf{E}_{21}} \begin{bmatrix} 1 & 1 & 3 \\ 0 & 2 & -5 \\ 1 & 2 & 0 \end{bmatrix} \xrightarrow{\mathbf{E}_{31}} \begin{bmatrix} 1 & 1 & 3 \\ 0 & 2 & -5 \\ 0 & 1 & -3 \end{bmatrix} \xrightarrow{\mathbf{E}_{32}} \begin{bmatrix} 1 & 1 & 3 \\ 0 & 2 & -5 \\ 0 & 0 & -\frac{1}{2} \end{bmatrix} = \mathbf{U}.$$

Then we have

$$\boldsymbol{E}_{32}\boldsymbol{E}_{31}\boldsymbol{E}_{21}(\boldsymbol{P}\boldsymbol{A}) = \boldsymbol{U}$$

where

$$\boldsymbol{P} = \begin{bmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 1 & 0 & 0 \end{bmatrix}, \ \boldsymbol{E}_{21} = \begin{bmatrix} 1 & 0 & 0 \\ -2 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}, \ \boldsymbol{E}_{31} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ -1 & 0 & 1 \end{bmatrix}, \text{ and } \boldsymbol{E}_{32} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & -\frac{1}{2} & 1 \end{bmatrix}.$$

Multiplying  $\boldsymbol{E}_1^{-1} \boldsymbol{E}_2^{-1} \boldsymbol{E}_3^{-1}$  to both sides, we can have

$$m{P}m{A} = m{E}_1^{-1} m{E}_2^{-1} m{E}_3^{-1} m{U} = m{L}m{U}$$

where

$$\boldsymbol{L} = \boldsymbol{E}_1^{-1} \boldsymbol{E}_2^{-1} \boldsymbol{E}_3^{-1} = \begin{bmatrix} 1 & 0 & 0 \\ 2 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 1 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & \frac{1}{2} & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 2 & 1 & 0 \\ 1 & \frac{1}{2} & 1 \end{bmatrix}.$$

The factorization  $\boldsymbol{P}\boldsymbol{A}=\boldsymbol{L}\boldsymbol{U}$  is hence given by

$$\begin{bmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 1 & 0 & 0 \end{bmatrix} \begin{bmatrix} 1 & 2 & 0 \\ 2 & 4 & 1 \\ 1 & 1 & 3 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 2 & 1 & 0 \\ 1 & \frac{1}{2} & 1 \end{bmatrix} \begin{bmatrix} 1 & 1 & 3 \\ 0 & 2 & -5 \\ 0 & 0 & -\frac{1}{2} \end{bmatrix}.$$

In order to factor  $\boldsymbol{A}$  into  $\boldsymbol{A} = \boldsymbol{L}_1 \boldsymbol{P}_1 \boldsymbol{U}_1$ , we first perform elimination as

$$\boldsymbol{A} = \begin{bmatrix} 1 & 2 & 0 \\ 2 & 4 & 1 \\ 1 & 1 & 3 \end{bmatrix} \stackrel{\boldsymbol{E}_{21}}{\Longrightarrow} \begin{bmatrix} 1 & 2 & 0 \\ 0 & 0 & 1 \\ 1 & 1 & 3 \end{bmatrix} \stackrel{\boldsymbol{E}_{31}}{\Longrightarrow} \begin{bmatrix} 1 & 2 & 0 \\ 0 & 0 & 1 \\ 0 & -1 & 3 \end{bmatrix}$$

and then do row exchange as

$$\begin{bmatrix} 1 & 2 & 0 \\ 0 & 0 & 1 \\ 0 & -1 & 3 \end{bmatrix} \xrightarrow{\mathbf{P}_{23}} \begin{bmatrix} 1 & 2 & 0 \\ 0 & -1 & 3 \\ 0 & 0 & 1 \end{bmatrix} = \mathbf{U}_1.$$

Therefore,

$$U_1 = P_1 E_{31} E_{21} A$$

where

$$\boldsymbol{P}_{1} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix}, \ \boldsymbol{E}_{21} = \begin{bmatrix} 1 & 0 & 0 \\ -2 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}, \text{ and } \boldsymbol{E}_{31} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ -1 & 0 & 1 \end{bmatrix}.$$

Multiplying  $\boldsymbol{E}_{21}^{-1} \boldsymbol{E}_{31}^{-1} \boldsymbol{P}_{1}^{-1}$  from the left to both sides, we can have

$$A = E_{21}^{-1} E_{31}^{-1} P_1^{-1} U_1$$

where  $\boldsymbol{P}_1^{-1} = \boldsymbol{P}_1$  and

$$\boldsymbol{L}_{1} = \boldsymbol{E}_{21}^{-1} \boldsymbol{E}_{31}^{-1} = \begin{bmatrix} 1 & 0 & 0 \\ 2 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 1 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 2 & 1 & 0 \\ 1 & 0 & 1 \end{bmatrix}.$$

The factorization  $\boldsymbol{A} = \boldsymbol{L}_1 \boldsymbol{P}_1 \boldsymbol{U}_1$  is hence given by

$$\begin{bmatrix} 1 & 2 & 0 \\ 2 & 4 & 1 \\ 1 & 1 & 3 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 2 & 1 & 0 \\ 1 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix} \begin{bmatrix} 1 & 2 & 0 \\ 0 & -1 & 3 \\ 0 & 0 & 1 \end{bmatrix}$$

(b) Do row exchange and elimination as

$$\boldsymbol{A} = \begin{bmatrix} 0 & 4 & 5 \\ 0 & 1 & 2 \\ 2 & 1 & 1 \end{bmatrix} \stackrel{\boldsymbol{P}_{13}}{\Longrightarrow} \begin{bmatrix} 2 & 1 & 1 \\ 0 & 1 & 2 \\ 0 & 4 & 5 \end{bmatrix} \stackrel{\boldsymbol{E}_{32}}{\Longrightarrow} \begin{bmatrix} 2 & 1 & 1 \\ 0 & 1 & 2 \\ 0 & 0 & -3 \end{bmatrix} = \boldsymbol{U} = \boldsymbol{E}_{32} \boldsymbol{P} \boldsymbol{A}.$$

We can have

$$PA = E_{32}^{-1}U = LU$$

where

$$\boldsymbol{P} = \begin{bmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 1 & 0 & 0 \end{bmatrix} \text{ and } \boldsymbol{L} = \boldsymbol{E}_{32}^{-1} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 4 & 1 \end{bmatrix}.$$

The factorization  $\boldsymbol{P}\boldsymbol{A}=\boldsymbol{L}\boldsymbol{U}$  is hence given by

$$\begin{bmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 1 & 0 & 0 \end{bmatrix} \begin{bmatrix} 0 & 4 & 5 \\ 0 & 1 & 2 \\ 2 & 1 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 4 & 1 \end{bmatrix} \begin{bmatrix} 2 & 1 & 1 \\ 0 & 1 & 2 \\ 0 & 0 & -3 \end{bmatrix}.$$

In order to factor  $\boldsymbol{A}$  into  $\boldsymbol{A} = \boldsymbol{L}_1 \boldsymbol{P}_1 \boldsymbol{U}_1$ , we perform elimination first as

$$\boldsymbol{A} = \begin{bmatrix} 0 & 4 & 5 \\ 0 & 1 & 2 \\ 2 & 1 & 1 \end{bmatrix} \stackrel{\boldsymbol{E}_{21}}{\Longrightarrow} \begin{bmatrix} 0 & 4 & 5 \\ 0 & 0 & \frac{3}{4} \\ 2 & 1 & 1 \end{bmatrix} \stackrel{\boldsymbol{P}'}{\Longrightarrow} \begin{bmatrix} 2 & 1 & 1 \\ 0 & 4 & 5 \\ 0 & 0 & \frac{3}{4} \end{bmatrix} = \boldsymbol{U}_{1} = \boldsymbol{P}' \boldsymbol{E}_{21} \boldsymbol{A}.$$

Then we can obtain

$$A = E_{21}^{-1} P'^{-1} U_1$$

where

$$\mathbf{P}' = \begin{bmatrix} 0 & 0 & 1 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix} \text{ and } \mathbf{E}_{21} = \begin{bmatrix} 1 & 0 & 0 \\ -\frac{1}{4} & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}.$$

Since

$$\boldsymbol{P}_{1} = \boldsymbol{P}'^{-1} = \boldsymbol{P}'^{T} = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{bmatrix} \text{ and } \boldsymbol{L}_{1} = \boldsymbol{E}'^{-1}_{21} = \begin{bmatrix} 1 & 0 & 0 \\ \frac{1}{4} & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

the factorization  $\boldsymbol{A} = \boldsymbol{L}_1 \boldsymbol{P}_1 \boldsymbol{U}_1$  is hence given by

$$\begin{bmatrix} 0 & 4 & 5 \\ 0 & 1 & 2 \\ 2 & 1 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ \frac{1}{4} & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{bmatrix} \begin{bmatrix} 2 & 1 & 1 \\ 0 & 4 & 5 \\ 0 & 0 & \frac{3}{4} \end{bmatrix}.$$